

KASS-based safety maps for autonomous

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#Systems for geolocation #KASS #Autonomous Vehicles #Connected Vehicles #GPS





The automotive industry is undergoing a regiol transition from Connected Wehides (CV) to Autonomous Vehicles (AV), Connected Wehides rely on vehicle-to-vehicle (Y2V) and vehicle infrastructure (Y2) communication to provide information to the driver for vehicle operation, in contrast, autonomous vehicles drive themselves using autonomous driving sensors successes, LDAR (Light Detection and Ranging), RADAR (Radio Detection and Ranging), and GPS (Robal Positioning System) receivers, highlighting a key difference between the two.

To fully realize autonomous vehicles, various technologies are being developed, and the latest autonomous vehicles are also referred to as 'Software Defined Vehicles' (SDV). A software a venicle differs from traditional venicles that require visits to operations, such as service centers, for software updates, instead, it allows software to be use hardware performance. This concept is similar to improving the performance of a smartphone's built-in camera through application updates.

Indicate for the operation of autonomous versions conducted. To address this issue, the Ministry of Land, Infrastructure and Transport is preparing to provide envires by establishing the Korea Augmentation Selected by Selecting (ASS), a Korean version of the Safetile Based Augmentation Sylene (SBAS), brown as the "Korean Precision GPS Positioning System". Once the KASS-basigned system is completed, the positioning error will be reduced to within 1-16 meters, enabling precise location-based autonomous driving, and it is expected that various services will be launched based on this signal system

ational examples. Subsequently, we plan to describe the strategy for their domestic implementation.

Need for KASS-based safety guidance







Uniform to a section of the control driver's location using high-precision maps, discrepancies between the vehicle's position on the man and its actual location are inevitable.

For example, as shown in [Figure 1], there are limitations in representing certain situation determined because road maintenance work is mistaken for a lane, leading to acciden situations where lane markings are not detected due to heavy rain or other weather conditions (Malfunction 3).

accurate location information. Based on this, a prominent example of an autonomous driving service is the "Super Cruise Map" of the American automobile company GMC. The Super Rep enables vehicles sold by GMC in the United States and Canada to recognize real rough autonomous driving sensors, providing Level 3 autonomous driving services on more than 400,000 miles (643,737 km) of road (see below [Figure 2]).



Union. As a result, vehicles manufactured and sold in Sweden, such as Volvo and Polestar, will be equipped with maps designed for autono detected. The project aims to be in operation by 2025.

KASS-based Security Map Construction Plan

As of 2012, the total langth of domestic mode in South Roma is 114,314 km, which is 2.5 ferms the circumference of the earth (46,250 km, making 1 a very long distance. Moreover, the management of these mode is diskded between the contral government and values local governments, making the task of creating an autonomous driving safely map for all domestic mode charges greated verbication. Currently, the Ministry of Long I firstitucture and Transport operated verbication for moments the autonomous driving road environment, but with only about lines such verbication in operation, it is difficult to comprehensively issues the condition of domestic roads. To address this, consideration should be given to be leveriging the 97273 official verbices owned by contral and local governments (as of November 2022). Since more than 98.5% of these registered official verbices are equipped with bacic autonomous driving and contractions of the properties of the section of a verbic road of information from the sections there were beloaded as which the condition of a verbic road of information from the sections there were beloaded as the condition of a verbic road of single of impaired due to been praid the to be remarking every, and sections where autonomous driving is impaired due to been maintenance, sections where autonomous driving is impaired due to been maintenance, sections where autonomous driving is impaired due to been maintenance, sections where autonomous driving is impaired due to been maintenance, sections where autonomous driving is impaired due to been maintenance, sections where autonomous driving is impaired due to been maintenance, sections where autonomous driving is impaired of the leave year.



Leveraging Collection Data
The data collected by the autonomous driving sensors of the official vehicles can be
incorporated into the traffic information provided by the read autonomies to the drivers, as
shown in [Figure 3] providing real vehicle-based autonomous driving information. By using the KASS signaling system, it will be possible to determine the success rate of autonomous driving for each lane within the same road section, such as the success rate for the first lane and the second lane. This would enable the provision of a more accurate and safer autonomous driving

Conclusion

Article 2, Paragraph 1, Item 1 of the Act on Promotion and Support of Commercialisation of Autonomous Vehicles defines an "autonom without the operation of a driver or passenger in accordance with Article 2, Paragraph 1, Item 3 of the Automobile Management Act".

7) In order for authoromous vehicles to recognize and Judge pither immunolings, they were possible for finishment Act."
7) In order for authoromous vehicles to recognize and Judge pither immunolings, they weed to other information using command that we equivalent to the human eye. The number of cameras required for authoromous driving may vary depending on the car manufacturer, but the minimum is two frost and rear cameras, and the maximum is eight, including front, rear, left, right, and binds spots.

4) It is a device that trans

ure sware.

5 OFS originated as NAVSTAR OPS for military applications such as weapons guidance, newigation and surveying, mapping, geodesy, and time synchronisation by the US Department of Defense, are is now used as a civilian global positioning system, with more than 24 satellites providing location information services around the word.

6) Military of Land, Infrastructure, Transport and Tourism, Press release, "XASS (Grean Air Satellite Service) to Improve the Accuracy of Location Information," Aviation Policy Division, 27
Ady 2012, p. L.

 This is a screen capture of the drive record (distriction) of a research vehicle of CPG, which was involved in an accident due to an actual lane recognition error.
 Autonomous driving is considered to be level 3 when the driver's hands and feet are free during driving according to the SAE J3016 standard set by the Society of Automotive Engineers. 11) See GMC, "What is Super Crusse?", GMC website (https://www.gmc.com/connectivity-technology/super-cruss, last valided 24 December 2023).

12) Anne-profit project organization created by the Sweddin government, large Sweddin companies such as Volve, Polestar and Efricason, and start-ups to develop and is addition to translanded the import systems.

13) mobility/fiship, a sub-project of Drive Sweden, is conducting various studies on safety manners.

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of roads and motorways*, Office for National Statistics website (https://kosis.kr/statl-ltml/statl-

15. See Shill alonghoon, "Analysis of the Current Status of Domestic Automobiles," Integrated Data Map website (https://www.bigdata-map.kridsataston/howistory.54, last visited 24 becentive 2023).

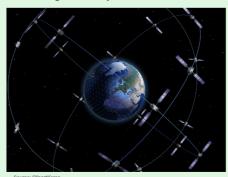
Industry Trends

GNSS Utilization Technology Trends

Global Navigation Satellite System (GNSS) is a system that uses artificial satellites to accurately determine the position of a target object. It is one of the key technologies of the Fourth Industrial Revolution and is widely used in next-generation mobile communications and smart mobility, where accurate location information is required. In particular, with the rapid development of the smart mobility industry, the use of GNSS in intelligent transportation systems is prominent.



Satellite Navigation Industry Trends



\$177.3 billion by 2040, up from \$98.3 billion in 2018. This has focused attention on both the am industries that provide GNSS-enabled services to consumers and the do es involved in component development. The number of GNSS recei expected to reach 6.5 billion by 2021, with a compound annual growth rate of 10%. Reveni for both the upstream and downstream industries are also expected to grow at a CAGR of 9.2% $\,$ to €49.2 billion by 2031 (based on €19.9 billion in 2021).

nt bank Morgan Stanley has predicted that the GNSS market will grow to

Utilization of the Satellite Navigation System of Smart Mobility

D-GNSS of Intelligent Transportation Systems

D-GNSS stands for Differential Global Navigation Satellite System, which is designed to eliminate errors that occur in traditional satellite navigation systems. It serves as a comple or enhancement to independent satellite navigation systems such as GPS. Accurate D-GNSS positioning data is essential for efficient Intelligent Transportation Systems, enabling monitoring of vehicle conditions such as speeding, congestion, and accidents.

D-GNSS data can be effectively used in bus operations. The data is used for speed analysis. monitoring vehicle congestion, estimating average route travel time, and analyzing driv fatigue. By using D-GNSS positioning data, it is possible to determine whether a bus has stopped at a designated bus stop and to estimate the average travel time based on segment specific time data.





Autonomous driving refers to a system in which a vehicle can drive itself by sensing the driving environment without human input. Recently, the application of autonomous driving has been ely expanding beyond passenger cars to vehicles such as trucks, drones, and buses. In rticular, autonomous trucks are characterized by high stability and cost-effectiveness. Using satellite navigation systems, they can assess road infrastructure and driving conditions, optimize operations to save fuel, and avoid unnecessary braking.

In 2021, South Korea's Ministry of Land, Infrastructure and Transport demonstrated the cluster driving (formation, maintenance and separation) of four autonomous trucks and the cluster driving matching service for the first time in the country at the Final Outcome Presentation of Autonomous Cooperative Cluster Driving Research and Development for Trucks. The demonstration took place on an approximately 80 km section of the Yeongdong Line and Central Inland Line highways. The successful process of sequentially merging and separating the autonomous driving trucks from the first to the fourth vehicle was demonstrated.

A self-driving drone

the United States and DHL in Germany. Autonomous drones are particularly advantageous for their ability to precisely deliver to high-rise buildings or apartment complexes, thanks to the use of satellite navigation systems that provide accurate location information.

UTM (Unmanned Traffic Management) is a prominent example of the use of autonomous drones in traffic management systems. Recently, the EU launched a UTM pilot project called EuroDRONE. The operation of EuroDRONE begins with the upload of waypoint information, including GPS coordinates and speed. The drone verifies the uploaded information, along with weather conditions and starting position, to determine whether the flight is authorized. During the flight, the drone continuously receives GPS data and calculates the distance to the destination, allowing it to draw flight trajectories in real time. This demonstration served as an opportunity to validate UTM's technology and services, and to explore potential future



Reference

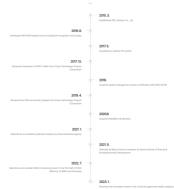


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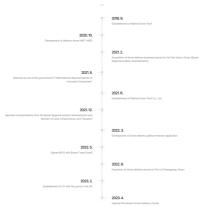








TIME LINE



Blockchain makes donating even more enjoyable, as the world becomes 1°C warmer







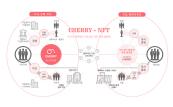




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